

# Optimally Robust Estimation by means of R Packages

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# Outline

1 Optimally Robust Estimators

2 R Packages

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# Infinitesimal Robust Setup

- **Smoothly parameterized** family of probability measures

$$\mathcal{P} = \{P_\theta \mid \theta \in \Theta\} \quad \Theta \subset \mathbb{R}^k \text{ (open)}$$

with  **$L_2$  derivative**  $\Lambda_\theta \in L_2^k(P_\theta)$ ,  $E_\theta \Lambda_\theta = 0$  and

- Fisher information of full rank

$$\mathcal{I}_\theta = E_\theta \Lambda_\theta \Lambda_\theta^\tau \quad \mathcal{I}_\theta \succ 0$$

- **Infinitesimal gross error model** with radius  $r \in (0, \infty)$

$$U(\theta, r) = \{(1 - r/\sqrt{n})_+ P_\theta + (1 \wedge r/\sqrt{n}) Q \mid Q \in \mathcal{M}_1(\mathcal{A})\}$$

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# Influence Curves (ICs) and AL Estimators

## Definition

*Influence curves (ICs):*

$$\Psi_2(\theta) = \{ \psi_\theta \in L_2^k(\mathbf{P}_\theta) \mid \mathbf{E}_\theta \psi_\theta = \mathbf{0}, \mathbf{E}_\theta \psi_\theta \Lambda_\theta^\top = \mathbb{I}_k \}$$

## Definition

*Asymptotically linear (AL) estimator:*

$$\sqrt{n}(S_n - \theta) = \frac{1}{\sqrt{n}} \sum_{i=1}^n \psi_\theta(y_i) + o_{\mathbf{P}_\theta^n}(n^0)$$

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# Optimally Robust Estimators

- **Optimally robust ICs**  $\tilde{\eta}_\theta$  w.r.t. maximum asymptotic MSE for various models (including regression and time series models) are derived in Rieder (1994), Rieder (2003) and Kohl (2005)
- Estimator construction by means of the one-step method

$$S_n(y_1, \dots, y_n) = \hat{\theta}_n(y_1, \dots, y_n) + \frac{1}{n} \sum_{i=1}^n \tilde{\eta}_\theta(y_i)$$

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# R Packages

**ROptEst:** Optimally robust estimation using S4 classes and methods

**RobLox:** Optimally robust ICs for normal location and scale

**ROptRegTS:** Optimally robust estimation for regression-type models using S4 classes and methods

**RobRex:** Optimally robust ICs for normal linear regression with unknown error scale

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